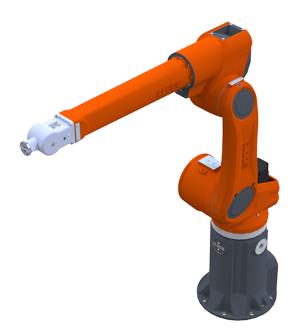


## **QIROX QRC-410-H**

6-axis robot mechanics with classic wrist, 4,100 mm working envelope and a high base for floor mounting

The QIROX QRC-410-H is a six-axis articulated arm robot. The robot is mounted in upright position on the floor or directly at a robot positioner. The QIROX QRC-410-H has a classic wrist where welding torches, flame cutters and other working tools with a weight of up to 10 kg can be mounted. The integration of a changing tool on the wrist allows the application of more processes with a robot.

- All-rounder: Carries out many different task due to the use of a changing tool and a maximum payload of 10 kg at the wrist
- Processes: Takes over all MIG/MAG and TIG welding processes, optionally leads a laser sensor and carries out cutting tasks
- Flexibility: Modular design for tailor-made systems, perfectly adapted to individual production requirements
- Dynamics: High dynamics due to slim product design, low weight and ergonomic shapes
- Quality: Repeatability, long service life and maintenance intervals







## **QIROX QRC-410-H**

Technical Data	
Series	WL
Design	Classic
Number of axes	6
Payload	10 kg
Working area	4100 mm
Mounting area	500x510
Robot weight	243 kg
Movetings	Radafing MIG/MAG welding MIG/MAG welding (WDD) MIG/MAG Tandem welding MIG/MAG Tandem welding (WDD) TIG welding TIG Welding (WDF) Laser cutting Laser welding Plasma and oxy-fuel cutting
Attachment parts	Greifer Offline Lasersensor Online Lasersensor Taktiler Taststift Wechselsystem

Process
<ul> <li>Handling</li> <li>MIG/MAG welding</li> <li>MIG/MAG welding (WDD)</li> <li>MIG/MAG Tandem welding</li> <li>MIG/MAG Tandem welding (WDD)</li> <li>TIG welding</li> <li>TIG Welding (WDF)</li> <li>Laser cutting</li> <li>Laser welding</li> </ul>
Plasma and oxy-fuel cutting

## Questions about the product?

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